



Modelling contiguity in spatial decision contexts

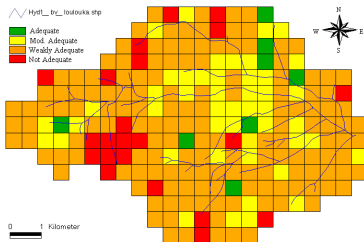
V. Brison, M. Pirlot

UMONS - Faculty of Engineering

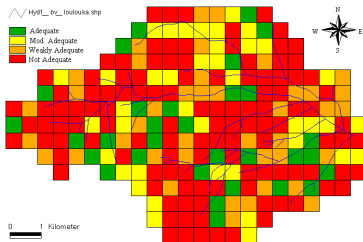
June 9th, 2017

We want to know which map is better

Response to the risk of degradation of the landscape
(Loulouka Basin, Burkina Faso)



Previous state

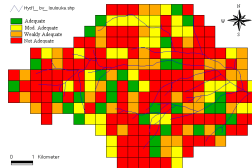
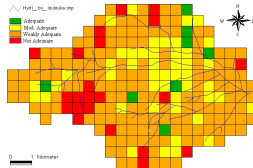


New state

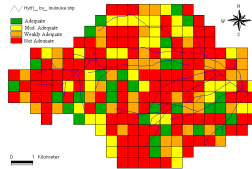
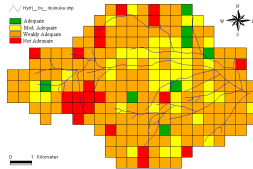
Evolution for the better or the worse?

Need of a model for comparing decision maps

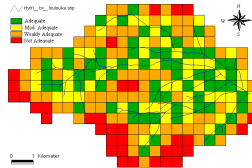
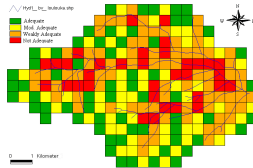
Problem 1



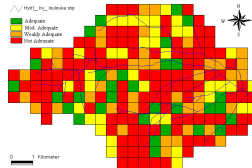
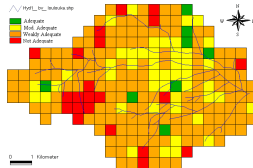
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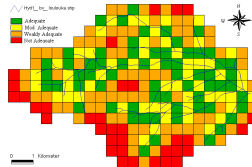
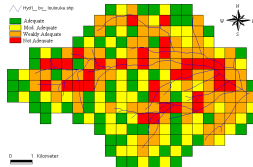
Problem 2



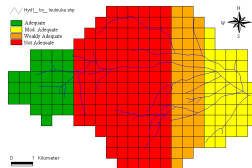
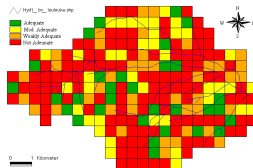
Problem 1



Problem 2



Problem 3



Comparing maps is a multi-criteria problem

S : territory composed of pixels

$s \in S$: pixel

$\gamma(s)$: evaluation of s on a common scale for all pixels

$\mathcal{C} = \{C_1, \dots, C_n\}$: the common evaluation scale, composed of n categories

$A = (S, \gamma)$: evaluated geographic map (= decision map)

\mathcal{A} : set of evaluated maps

\succsim : preference relation on \mathcal{A}

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Comparison with a MCDA problem

maps = alternatives

evaluations associated with the pixels = criteria

Remark: common evaluation scale for all pixels \Rightarrow commensurable scales

- 1 Comparing maps in a basic way
- 2 Taking geographic aspects into account
- 3 Taking contiguity into account

Model 1:

Comparing maps in a basic way

We use an expected utility model

Expected utility model

$$A = (S, \gamma), B = (S, \delta)$$

$$A \succsim B \iff \frac{1}{N} \sum_{s \in S} u(\gamma(s)) \geq \frac{1}{N} \sum_{s \in S} u(\delta(s)),$$

with $\gamma(s) \in \{C_1, \dots, C_n\}$ and N is the total number of pixels

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Rewriting the expected utility model

$$u(\gamma(s)) = u_i \text{ if } \gamma(s) = C_i$$

$$x_i(A) = \frac{|\{s \in S: \gamma(s) = C_i\}|}{N}$$

$$A \succsim B \iff \sum_{i=1}^n x_i(A) u_i \geq \sum_{i=1}^n x_i(B) u_i$$

The model assumes that the region is homogeneous

Hypothesis

We assume that the whole region is *homogeneous*:

$$x(A) = x(B) \Rightarrow A \sim B$$

with $x(A) = (x_1(A), x_2(A), \dots, x_n(A))$ the area distribution in categories of map A

Are these two maps really indifferent?

- Model 1 assumes that the region is homogeneous

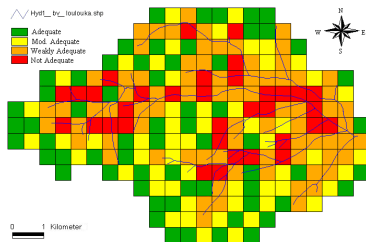


Figure : State 1

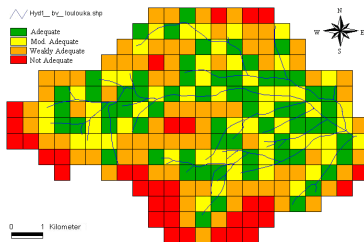


Figure : State 2

Are these two maps really indifferent?

- Model 1 assumes that the region is homogeneous

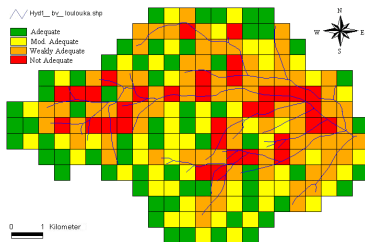


Figure : State 1

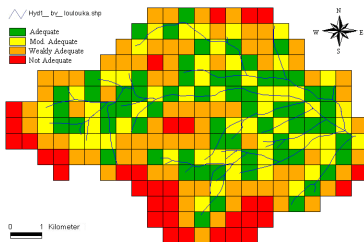


Figure : State 2

- Model 2 assumes that the region is composed of several homogeneous sub-regions (defined by a geographic aspect)

Model 2:

Taking geographic aspects into account

We generalize the expected utility model

$$A \succsim B \iff \sum_{j=1}^m \sum_{i=1}^n x_{ij}(A) u_j(E_{ij}) \geq \sum_{j=1}^m \sum_{i=1}^n x_{ij}(B) u_j(E_{ij})$$

where

j is the homogeneous sub-region

i is the category

$x_{ij}(\cdot)$ is the proportion of the surface of region j assigned to category i

$u_j(E_{ij})$ is the utility associated with the homogeneous sub-region j entirely assigned to category i

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Hypothesis

We assume that comparing maps only depends on the comparison of the area distributions of the homogeneous sub-regions: for all A, B, C, D , if $A \succsim B$, $x_j(A_j) = x_j(C_j)$ and $x_j(B_j) = x_j(D_j)$ for all j , then $C \succsim D$ with $x_j(\cdot) = (x_{1j}(\cdot), \dots, x_{nj}(\cdot))$

Taking contiguity into account

Are these maps really indifferent?

Same distribution

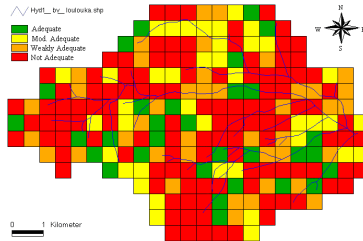


Figure : Scattered map

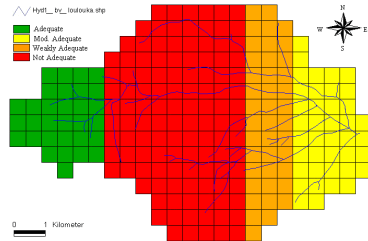


Figure : Clustered map

Are these maps really indifferent?

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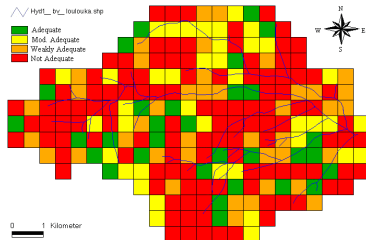


Figure : Scattered map

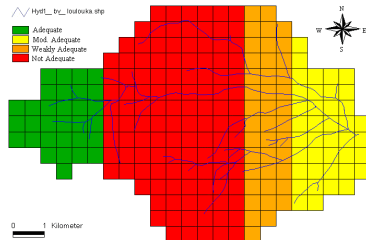


Figure : Clustered map

⇒ Model based on the Choquet integral

The Choquet integral

No interaction:

$$\sum_{s \in S} m(\{s\}) u(\gamma(s))$$

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Pairwise interactions

$$\sum_{s \in S} m(\{s\}) u(\gamma(s)) + \sum_{s, t \in S} m(\{s, t\}) \min(u(\gamma(s)), u(\gamma(t)))$$

The Choquet integral

No interaction:

$$\sum_{s \in S} m(\{s\}) u(\gamma(s))$$

Pairwise interactions + triple interactions

$$\begin{aligned} \sum_{s \in S} m(\{s\}) u(\gamma(s)) &+ \sum_{s, t \in S} m(\{s, t\}) \min(u(\gamma(s)), u(\gamma(t))) \\ &+ \sum_{r, s, t \in S} m(\{r, s, t\}) \min(u(\gamma(r)), u(\gamma(s)), u(\gamma(t))) \end{aligned}$$

The Choquet integral

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$$\sum_{s \in S} m(\{s\}) u(\gamma(s))$$

Pairwise interactions + triple interactions + ...

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Choquet integral:

$$C_m(u(\gamma(s_1)), \dots, u(\gamma(s_N))) = \sum_{Y \subseteq \{1, \dots, N\}} m(Y) \min_{i \in Y} u(\gamma(s_i))$$

The Choquet integral

No interaction:

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Pairwise interactions + triple interactions + ...

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Interactions between K pixels \Rightarrow K -additive Choquet integral

The Choquet integral is usually defined by a capacity...

Capacity

Let $I = \{1, \dots, N\}$. A capacity μ over I is a function $\mu : 2^I \rightarrow [0, 1]$ s.t.

- 1 $\mu(\emptyset) = 0$
- 2 $\mu(I) = 1$
- 3 $\forall A, B \subseteq I, A \subseteq B \Rightarrow \mu(A) \leq \mu(B)$

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Möbius transform

Let μ be a capacity over $I = \{1, \dots, N\}$. The Möbius transform of μ is

$$m(A) = \sum_{B \subseteq A} (-1)^{|A \setminus B|} \mu(B), \forall A \subseteq I$$

... but we are working with its Möbius transform

Choquet integral

Let $I = \{1, \dots, N\}$ and $x := (x_1, \dots, x_N) \in \mathbb{R}^N$

$$C_m(x) = \sum_{A \subseteq I} m(A) \bigwedge_{i \in A} x_i$$

... but we are working with its Möbius transform

Choquet integral

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$$C_m(x) = \sum_{A \subseteq I} m(A) \bigwedge_{i \in A} x_i$$

k -additive capacity

Let $I = \{1, \dots, N\}$. A capacity μ over I is k -additive ($0 < k \leq N$) if $m_\mu(A) = 0 \forall A \subseteq I$ s.t. $|A| > k$ and if $\exists A \subseteq I$ s.t. $|A| = k$ and $m_\mu(A) \neq 0$

We set the contiguity structure

2 pixels are contiguous \iff they have a common edge

We only consider pairwise interactions

We define

$$\begin{aligned} m(\{s\}) &= \alpha \\ m(\{s, t\}) &= \begin{cases} \beta & \text{if } s, t \text{ are contiguous} \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

$\beta > 0 \Rightarrow$ advantage to contiguity

$\beta < 0 \Rightarrow$ disadvantage to contiguity

$\beta = 0 \Rightarrow$ contiguity has no influence

We impose 3 conditions on m

3 conditions (Chateauneuf and Jaffray (1989)):

1 $m(\emptyset) = 0$

2 $\sum_{R \subseteq S} m(R) = 1$

3 $\sum_{R \subseteq T, R \ni s} m(R) \geq 0, \forall R \subseteq S, \forall s \in S$

We rewrite the Choquet integral

$$C_m(u, A) = \sum_{s \in S} m(\{s\})u(\gamma(s)) + \sum_{\substack{s, t \in S \\ s, t \text{ contiguous}}} m(\{s, t\}) \min(u(\gamma(s)), u(\gamma(t)))$$

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We rewrite the Choquet integral

$$\begin{aligned}
 C_m(u, A) &= \sum_{s \in S} m(\{s\})u(\gamma(s)) + \sum_{\substack{s, t \in S \\ s, t \text{ contiguous}}} m(\{s, t\}) \min(u(\gamma(s)), u(\gamma(t))) \\
 &= \alpha \sum_{s \in S} u(\gamma(s)) + \beta \left(\sum_{\substack{s, t \in S \\ s, t \text{ contiguous}}} \min(u(\gamma(s)), u(\gamma(t))) \right) \\
 &= \alpha \sum_{i=1}^n n_i(A)u_i + \beta \sum_{i=1}^n m_i(A)u_i \\
 &= \sum_{i=1}^n u_i(\alpha n_i(A) + \beta m_i(A))
 \end{aligned}$$

where $n_i(A)$ = number of pixels s s.t. $u(\gamma(s)) = u_i$ and $m_i(A)$ = number of contiguous pairs $\{s, t\}$ s.t. $\min(u(\gamma(s)), u(\gamma(t))) = u_i$

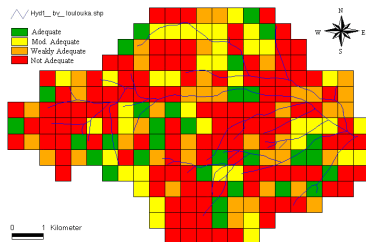


Figure : Scattered map

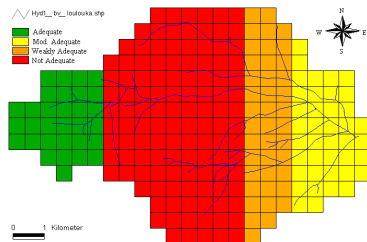


Figure : Clustered map

$$\begin{aligned}
 C_m(u, A) &= \alpha \sum_{i=1}^n n_i(A)u_i + \beta \sum_{i=1}^n m_i(A)u_i \\
 &= \alpha(31u_1 + 40u_2 + 41u_3 + 117u_4) + \beta(5u_1 + 43u_2 + 58u_3 + 313u_4) \\
 C_m(u, B) &= \alpha(31u_1 + 40u_2 + 41u_3 + 117u_4) + \beta(49u_1 + 75u_2 + 64u_3 + 231u_4)
 \end{aligned}$$

- $\beta > 0 \Rightarrow$ the clustered map is better
- $\beta < 0 \Rightarrow$ the scattered map is better

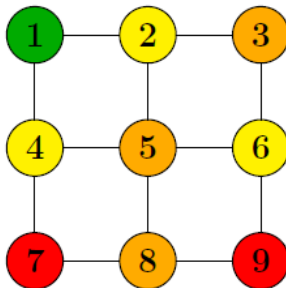
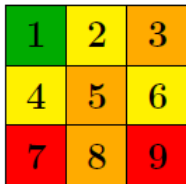
Question: what are the conditions underlying this model?

We represent contiguity by a graph

-  Category C_1
-  Category C_2
-  Category C_3
-  Category C_4

1	2	3
4	5	6
7	8	9

We represent contiguity by a graph



$$G = (I, E)$$

Wakker characterizes a “general” Choquet integral

Characterization (Wakker 1989)

Under some topological assumptions, the following two statements are equivalent:

(i) \succsim can be represented by a Choquet integral

$$C_m(u(x_1), \dots, u(x_N)) = \sum_{Y \subseteq \{1, \dots, N\}} m(Y) \min_{i \in Y} u(x_i)$$

(ii) The binary relation \succsim does not reveal comonotonic contradictory tradeoffs

We use the following notation

$I = \{1, \dots, N\}$: set of criteria

$X^N = X \times \dots \times X$: set of alternatives

\succsim : preference relation on X^N

\succsim_0 : preference relation on X

Wakker works with comonotonic alternatives

Comonotonic alternatives

$x = (x_1, \dots, x_N)$ and $y = (y_1, \dots, y_N)$ are comonotonic if
 $\forall i, j \in \{1, \dots, N\}$

$$x_i \succ_0 x_j \Rightarrow \text{not } (y_j \succ_0 y_i)$$

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Students	Maths	Physics	Literature
A	18	16	10
B	10	12	18
C	14	15	15

We illustrate Wakker's axiom

Students	Maths	Physics	Literature
A	18	12	6
B	16	11	10
A'	14	12	6
B'	13	11	10
C	18	12	10
D	16	12	12
C'	14	12	10
D'	13	12	12

We illustrate Wakker's axiom

Students	Maths	Physics	Literature	Mean
A	18	12	6	12
B	16	11	10	12.3
A'	14	12	6	10.6
B'	13	11	10	11.3
C	18	12	10	13.3
D	16	12	12	13.3
C'	14	12	10	12
D'	13	12	12	12.3

$$A \prec B \quad A' \sim B' \quad C \sim D \quad C' \prec D'$$

Wakker's axiom is based on the revelation of comonotonic contradictory tradeoffs

Comonotonic contradictory tradeoffs

\succsim reveals comonotonic contradictory tradeoffs if $\exists x_{-i}\alpha, y_{-i}\beta, x_{-i}\gamma, y_{-i}\delta$ comonotonic such that

$$x_{-i}\alpha \succsim y_{-i}\beta \text{ and } x_{-i}\gamma \succsim y_{-i}\delta$$

and if $\exists v_{-j}\alpha, w_{-j}\beta, v_{-j}\gamma, w_{-j}\delta$ comonotonic such that

$$v_{-j}\alpha \succsim w_{-j}\beta \text{ and } v_{-j}\gamma \prec w_{-j}\delta$$

We illustrate Wakker's axiom

Students	Maths	Physics	Literature	Mean
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C'	14	12	10	12
D'	13	12	12	12.3

$$A \prec B \quad A' \sim B' \quad C \sim D \quad C' \prec D'$$

Wakker characterizes a “general” Choquet integral

Characterization (Wakker 1989)

Under some topological assumptions, the following two statements are equivalent:

(i) \succsim can be represented by a Choquet integral

$$C_m(u(x_1), \dots, u(x_N)) = \sum_{Y \subseteq \{1, \dots, N\}} m(Y) \min_{i \in Y} u(x_i)$$

(ii) The binary relation \succsim does not reveal comonotonic contradictory tradeoffs

We obtain a particular Choquet integral

Characterization

Let $G = (I, E)$ be an interaction graph that does not contain any complete subgraph with 3 nodes or more. Under the same topological assumptions as Wakker's, the following two statements are equivalent:

(i) \succsim can be represented by a **2-additive** Choquet integral such that

$$m(\{s, t\}) = 0 \text{ if } \{s, t\} \notin E$$

(ii) The binary relation \succsim does not reveal **G-comonotonic** contradictory tradeoffs

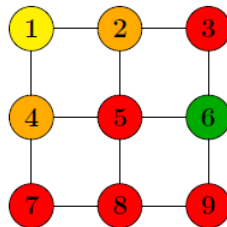
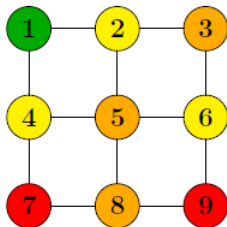
We work with G -comonotonic alternatives

G -Comonotonic alternatives

$x = (x_1, \dots, x_N)$ and $y = (y_1, \dots, y_N)$ are G -comonotonic if $\forall \{i, j\} \in E$

$$x_i \succ_0 x_j \Rightarrow \text{not } (y_j \succ_0 y_i)$$

Here are two G -comonotonic maps



Comonotonicity implies G -comonotonicity

Comonotonic $\Rightarrow G$ -comonotonic

Comonotonicity implies G -comonotonicity

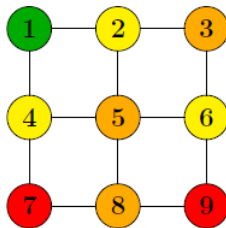
Comonotonic $\Rightarrow G$ -comonotonic

G -comonotonic $\not\Rightarrow$ comonotonic

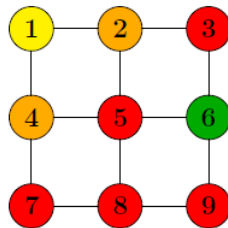
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Comonotonic $\Rightarrow G$ -comonotonic

G -comonotonic $\not\Rightarrow$ comonotonic



$$x_1 \succ_0 x_6$$



$$y_6 \succ_0 y_1$$

Our characterization is based on the revelation of G -comonotonic contradictory tradeoffs

Revelation of G -comonotonic contradictory tradeoffs

\succsim reveals G -comonotonic contradictory tradeoffs if
 $\exists x_{-i}\alpha, y_{-i}\beta, x_{-i}\gamma, y_{-i}\delta$ G -comonotonic such that

$$x_{-i}\alpha \succsim y_{-i}\beta \text{ and } x_{-i}\gamma \succsim y_{-i}\delta$$

and if $\exists v_{-j}\alpha, w_{-j}\beta, v_{-j}\gamma, w_{-j}\delta$ G -comonotonic such that

$$v_{-j}\alpha \succsim w_{-j}\beta \text{ and } v_{-j}\gamma \prec w_{-j}\delta$$

Our axiom implies Wakker's axiom

Comonotonic \Rightarrow G -comonotonic

Our axiom implies Wakker's axiom

Comonotonic \Rightarrow G -comonotonic

Revelation of comonotonic contradictory tradeoffs \Rightarrow
revelation of G -comonotonic contradictory tradeoffs

Our axiom implies Wakker's axiom

Comonotonic \Rightarrow G -comonotonic

Revelation of comonotonic contradictory tradeoffs \Rightarrow
revelation of G -comonotonic contradictory tradeoffs

Non revelation of G -comonotonic contradictory tradeoffs \Rightarrow
non revelation of comonotonic contradictory tradeoffs

We obtain a particular Choquet integral

Characterization

Let $G = (I, E)$ be an interaction graph. Under the same topological assumptions as Wakker's, the following two statements are equivalent:

(i) \succsim can be represented by

$$C_m(u(x_1), \dots, u(x_N)) = \sum_{Y \subseteq \{1, \dots, N\}} m(Y) \min_{i \in Y} u(x_i)$$

and

$m(Y) = 0$ if Y is not a complete subgraph

(ii) The binary relation \succsim does not reveal G -comonotonic contradictory tradeoffs

We obtain a particular Choquet integral

Characterization

Let $G = (I, E)$ be an interaction graph that does not contain any complete subgraph with 3 nodes or more. Under the same topological assumptions as Wakker's, the following two statements are equivalent:

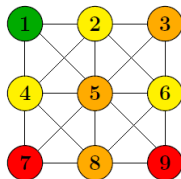
- (i) \succsim can be represented by a **2-additive** Choquet integral such that
$$m(\{s, t\}) = 0 \text{ if } s, t \text{ are not linked by an edge in } G$$
- (ii) The binary relation \succsim does not reveal **G-comonotonic** contradictory tradeoffs

We obtain a particular Choquet integral

Characterization

Let $G = (I, E)$ be an interaction graph that does not contain any complete subgraph with 5 nodes or more. Under the same topological assumptions as Wakker's, the following two statements are equivalent:

- (i) \succsim can be represented by a **4-additive** Choquet integral such that
 $m(Y) = 0$ if Y contains two nodes not linked by an edge in G
- (ii) The binary relation \succsim does not reveal G -comonotonic contradictory tradeoffs



We obtain a particular Choquet integral

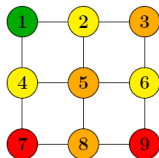
Characterization

Let $G = (I, E)$ be an interaction graph that does not contain any complete subgraph with $K + 1$ nodes or more. Under the same topological assumptions as Wakker's, the following two statements are equivalent:

- (i) \succsim can be represented by a K -additive Choquet integral such that
 $m(Y) = 0$ if Y contains two nodes not linked by an edge in G
- (ii) The binary relation \succsim does not reveal G -comonotonic contradictory tradeoffs

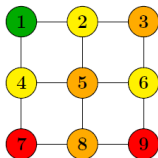
Going back to maps comparison

2 pixels are contiguous \iff they have a common edge
We only consider pairwise interactions



Going back to maps comparison

2 pixels are contiguous \iff they have a common edge
 We only consider pairwise interactions



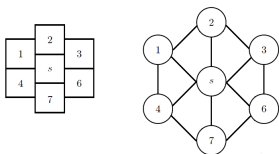
$$m(\{s\}) = \alpha$$

$$m(\{s, t\}) = \begin{cases} \beta & \text{if } s, t \text{ are contiguous} \\ 0 & \text{otherwise} \end{cases}$$

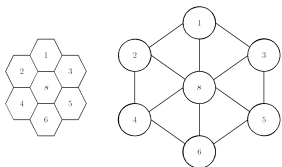
$$C_m(u, A) = \sum_{s \in S} m(\{s\})u(\gamma(s)) + \sum_{\substack{s, t \in S \\ s, t \text{ contiguous}}} m(\{s, t\}) \min(u(\gamma(s)), u(\gamma(t)))$$

$$= \sum_{i=1}^n u_i(\alpha n_i(A) + \beta m_i(A))$$

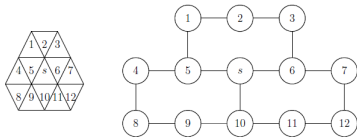
Going back to maps comparison



3-additive Choquet integral



3-additive Choquet integral



2-additive Choquet integral

Going back to maps comparison

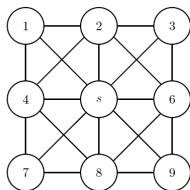
Four color theorem: with four colors, it is possible to color any connected map in such a way that two regions sharing a common boundary (not reduced to a single point) do not share the same color

⇒ any connected map has no complete subgraph with five nodes

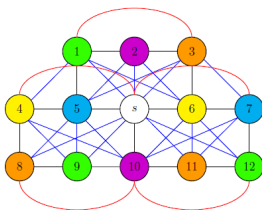
⇒ 4-additive Choquet integral

We can consider more pairwise interactions

1	2	3
4	s	6
7	8	9



4-additive Choquet integral

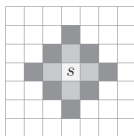


6-additive Choquet integral

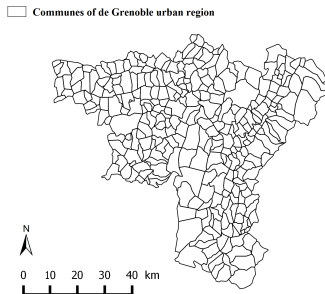
We can consider more pairwise interactions

$$\begin{aligned}
 C_m(u, A) = & \alpha \sum_{s \in S} u(\gamma(s)) + \beta_1 \sum_{\{s, t\}: d_1(s, t)=1} \min(u(\gamma(s)), u(\gamma(t))) \\
 & + \beta_2 \sum_{\{s, t\}: d_1(s, t)=2} \min(u(\gamma(s)), u(\gamma(t))) \\
 & + \dots \\
 & + \beta_k \sum_{\{s, t\}: d_1(s, t)=k} \min(u(\gamma(s)), u(\gamma(t))),
 \end{aligned}$$

with $d_1(s, t)$ the L_1 -distance defined by $d_1(s, t) = |s_1 - t_1| + |s_2 - t_2|$,
 $s = (s_1, s_2), t = (t_1, t_2)$



We can consider an irregular sub-division of the territory



$$m(\{s\}) = \alpha$$
$$m(\{s, t\}) = \begin{cases} \beta & \text{if } s, t \text{ are contiguous} \\ 0 & \text{otherwise} \end{cases}$$

α can depend on the surface area of s

β can depend on the length of the common border between s and t

Conclusion

- Our characterization depends on the interaction structure

Conclusion

- Our characterization depends on the interaction structure
- Our interactions are well-defined in terms of contiguity

Favored configuration with $\beta > 0$

0	0	1	1	2	2
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Favored configuration with $\beta < 0$

2	0	2	0	1	1
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Thank you for your attention





Modelling contiguity in spatial decision contexts

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